

## Computer Vision I: Low-Middle Level Vision Homework Exercise #2

(total 10 points)

Due: November 28th 11:59 PM.

**Problem 1** (Minimax entropy learning, 3 points).

This question aims to refresh the proof process in minimax entropy learning. Let  $p(\mathbf{I})$  be a FRAME model with  $K$  histograms matched to the underlying model  $f(\mathbf{I})$

$$p(\mathbf{I}; \Theta) = \frac{1}{Z(\Theta)} \exp\left\{-\sum_{i=1}^K \langle \lambda_i, H_i(\mathbf{I}) \rangle\right\} \quad (1)$$

The parameter  $\Theta = (\lambda_1, \dots, \lambda_K)$  is learned so that the following constraints are satisfied.

$$E_p[H_i(\mathbf{I})] = E_f[H_i(\mathbf{I})] = h_i, \quad i = 1, 2, \dots, K. \quad (2)$$

- **Q1:** Derive the following equation:

$$\frac{\partial \log Z}{\partial \lambda_i} = -E_p[H_i(\mathbf{I})].$$

- **Q2:** Let  $\ell(\Theta)$  be the log-likelihood for one observed image  $\mathbf{I}^{\text{obs}}$ , prove that

$$\frac{\partial^2 \ell(\Theta)}{\partial \lambda_i \partial \lambda_j} = -\frac{\partial^2 \log Z}{\partial \lambda_i \partial \lambda_j} \quad (3)$$

$$= -E_p[(H_i(\mathbf{I}) - h_i)(H_j(\mathbf{I}) - h_j)], i, j \in \{1, 2, \dots, K\} \quad (4)$$

*comment: Thus the second derivative of  $\ell(\Theta)$  is a negative covariance matrix. So  $\ell(\Theta)$  has a single maximum solution.*

Now suppose we extract a new feature from the dictionary  $F_+ \in \Delta$ , and augment the model to

$$p_+(\mathbf{I}; \Theta_+) = \frac{1}{Z(\lambda_+)} \exp\left[-\sum_{\alpha=1}^K \langle \lambda_\alpha^*, H_\alpha(\mathbf{I}) \rangle - \langle \lambda_+, H_+(\mathbf{I}) \rangle\right] \quad (5)$$

The new parameter  $\Theta_+ = (\lambda_1^*, \dots, \lambda_K^*, \lambda_+)$  is learned to not only satisfy the  $K$  constraints specified in equation (2), but also an extra condition:

$$E_{p_+}[H_+(\mathbf{I})] = E_f[H_+(\mathbf{I})] = h_+. \quad (6)$$

Note: To match all the  $K + 1$  statistical constraints, the existing parameters ( $\lambda_\alpha \rightarrow \lambda_\alpha^*, i = 1, 2, \dots, K$ ) must be updated when we introduce new features (marginal) because all features are correlated.

- **Q3:** Derive the steps for proving the following theorem

$$KL(f||p) - KL(f||p_+) = KL(p_+||p).$$

**Problem 2** (Learning by information projection, 2 points )

Suppose that we are learning the underlying probability model  $f(\mathbf{I})$  of image  $\mathbf{I}$ . We start with an initial probability model, denoted as  $q(\mathbf{I})$ , and observe that  $q(\mathbf{I})$  has a different marginal probability over a macroscopic feature  $H_i(\mathbf{I})$ :

$$E_q[H_i(\mathbf{I})] \neq E_f[H_i(\mathbf{I})] = h_i,$$

where  $h_i$  is estimated from a set of examples sampled from  $f(\mathbf{I})$ . To improve the current model, we learn a new probability model  $p(\mathbf{I})$  so that it reproduces this marginal statistics feature ( $p(\mathbf{I})$  may not necessarily replicate all the marginal probabilities that model  $q(\mathbf{I})$  has matched previously). We denote the set of models that satisfy this constraint equation by,

$$\Omega_i = \{p : E_p[H_i(\mathbf{I})] = E_f[H_i(\mathbf{I})] = h_i.\}$$

Now, among all the  $p(\mathbf{I})$  in  $\Omega_i$ , we choose one that is closest to  $q(\mathbf{I})$  so that it preserves the learning history.

$$p^* = \arg \min_{p \in \Omega_i} KL(p||q) = \arg \min_{p \in \Omega_i} \int p(\mathbf{I}) \log \frac{p(\mathbf{I})}{q(\mathbf{I})} d\mathbf{I}.$$

1. Derive the formula of  $p(\mathbf{I})$  by leveraging the Euler-Lagrange equation (Tips: (I) constrained optimization).
2. Prove that  $KL(f||q) - KL(f||p) = KL(p||q)$ . (Remark: Since  $D(p||q) > 0$ ,  $p$  is closer to  $f$  than  $q$ ).
3. Show that this optimization satisfies the maximum entropy principle when  $q(\mathbf{I})$  is a uniform distribution.

**Problem 3** (Information projection, 3 points)

Considering the feature pursuit in a family of models,

$$p_0(x) \rightarrow p_1(x) \rightarrow \dots \rightarrow p_K(x) \sim f(x).$$

where

$$p_K(x; \Theta_K) = \frac{1}{Z_K} \exp\left\{-\sum_{i=1}^K \lambda_i h_i(x)\right\}.$$

For simplicity, we treat  $\lambda_i$  as a scalar rather than a vector.

In the minimax entropy process, when we add a new feature statistics  $h_K(x)$ , we need to update all the parameters  $\lambda_i = 1, \dots, K$  in the new model  $p_K(x; \Theta_K)$  by MLE, so that all the  $K$  constraint equations are satisfied,

$$E_{p_K}[h_i(x)] = h_i^{\text{obs}}, \quad i = 1, 2, \dots, K.$$

In a different method, we can pursue a series of models in the following way,

$$q_0(x) \rightarrow q_1(x) \rightarrow \dots \rightarrow q_K(x) \sim f(x).$$

with

$$q_K(x) = \frac{1}{z_K} q_{K-1}(x) \exp\{-\beta_K h_K(x)\}.$$

In this model,  $\beta_K$  is decided by the new constraint

$$E_{q_K}[h_K(x)] = E_f[h_K(x)] \approx h_K^{\text{obs}}.$$

In comparison to the previous p-series, the q-series observes the constraints one-by-one, and fixes the previous parameters  $\beta_i, i = 1, 2, \dots, K - 1$  when we learn  $\beta_K$ , i.e.

$$q_K(x; ) = \frac{1}{z_1 z_2 \dots z_K} q_o(x) \exp\left\{-\sum_{i=1}^K \beta_i h_i(x)\right\}.$$

1. For the q-series, derive the formula for  $\frac{\partial \log z_K}{\partial \beta_k}$ .
2. Suppose we denote by  $Z_K = z_1 z_2 \dots z_{K-1}$  as the normalizing function for  $q_K(x)$ , derive  $\frac{\partial^2 \log Z_K}{\partial \beta_i \partial \beta_j}$ ,  $\forall i, j \leq K$ .
3. Prove that  $KL(f||q_K) - KL(f||q_{K+1}) = KL(q_{K+1}||q_K) \geq 0$ , and prove the q-series will converge to  $f$

**Problem 4** (Typical set, 2 points)

Suppose we toss a coin  $N$  times and observe a 0/1 sequence (for head and tail respectively),

$$S_N = (x_1, x_2, \dots, x_N), \quad x_i \in \{0, 1\}.$$

$S_N$  is said to be of *type*  $q$  (i.e. the frequency of 1 is  $q$  in the sequence) with  $q = \frac{1}{N} \sum_{i=1}^N x_i$ .

Let  $\Omega(q)$  be the set of all sequences  $S_N$  of type  $q$ . For simplicity, we discretize  $q$  to finite precision.

1. What is the cardinality of  $\Omega(q)$  for  $q = 0.2$  and  $q = 0.5$  respectively? (Suppose we only care about the exponential order or rate).

2. Suppose we know that the underlying probability is  $x_i = 1$  (or  $x_i = 0$ ) with probability  $p$  (or  $1 - p$  respectively), by sampling from this probability  $N$  times, what is the probability  $p(S_N)$  that we observe a sequence  $S_N \in \Omega(q)$ ? What is the total probability mass  $p(\Omega(q))$  for all the sequences in set  $\Omega(q)$ ?
3. In the above question, show that as  $N \rightarrow \infty$ , only sequences from the type  $p$ , i.e. set  $\Omega(p)$ , can be observed.